

Quickselect under Yaroslavskiy's Dual-Pivoting Algorithm

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Menorca

Selection

Consider the following problem

The Selection Problem

Given an **unsorted** array A of n data elements,
find the **m-th smallest** element.

• Applications

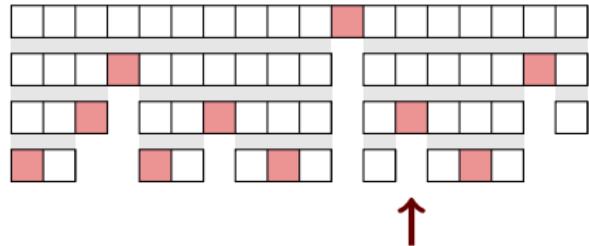
- estimate distribution of data collection in statistics
- world rankings in sports

• Algorithms

- **trivial solution:** `sort(A); return A[m];` $\mathcal{O}(n \log n)$
- linear worst case possible: *Median-of-Medians* (Blum et al.)
but rather slow in practice (compared to sorting!)
- Hoare 1961: **Quicksort** idea usable for selection

From Quicksort to Quickselect

Sort whole array by Quicksort

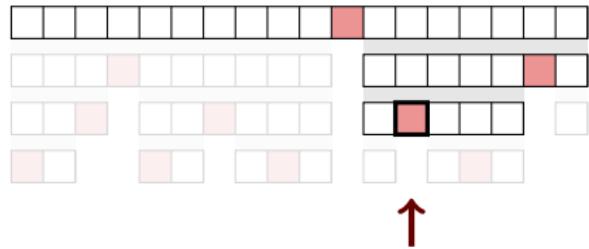


- Markus Nebel just showed:
Yaroslavskiy's partitioning can **speed up Quicksort**

Does success of dual partitioning in sorting carry over to selection?

From Quicksort to Quickselect

Can prune many branches



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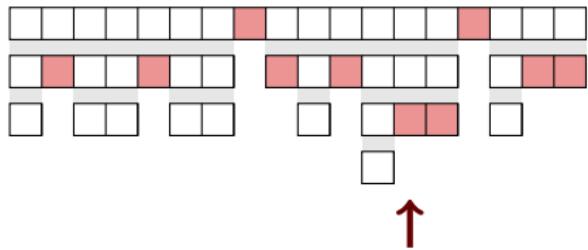
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Dual Pivot Quicksort

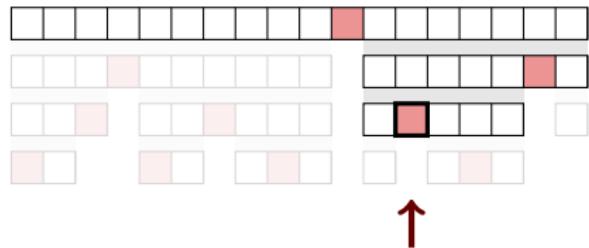


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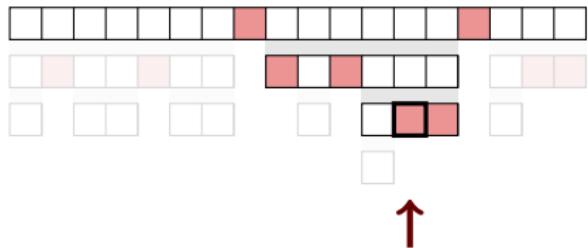
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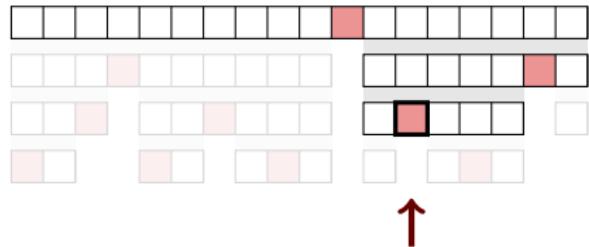


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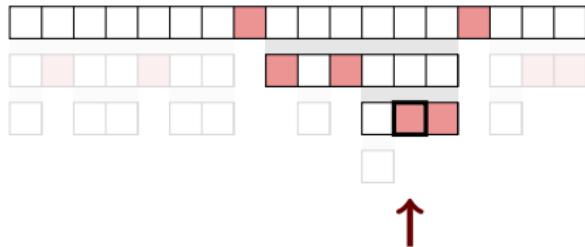
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Does success of dual partitioning in sorting carry over to selection?

Notation

- Analyse (**random**) number of data **comparisons** $C_n^{(m)}$ to select from random permutation
 - $P < Q$: (random) **ranks** of the two pivots
 - ↪ **subarray sizes** determined by P and Q:

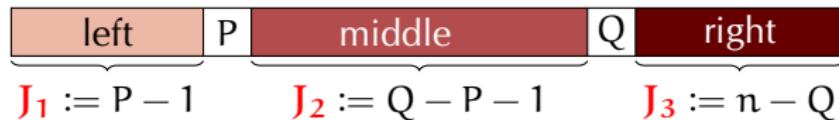


- selection continues recursively in corresponding events
 - left subarray, if $m < P$
 - middle subarray, if $P < m < Q$
 - right subarray, if $Q < m$
 - or terminates if $m = P$ or $m = Q$

$$\begin{aligned}\mathcal{E}_1 &:= \{m < P\} \\ \mathcal{E}_2 &:= \{P < m < Q\} \\ \mathcal{E}_3 &:= \{Q < m\}\end{aligned}$$

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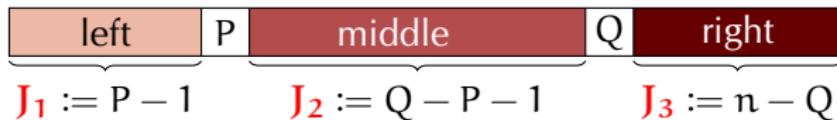


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Quickselect Recurrence

- Yaroslavskiy's partitioning preserves randomness
- ↝ can set up **recurrence** for the **distribution** of $C_n^{(m)}$:

$$C_n^{(m)} \stackrel{\text{D}}{=} T_n + \begin{cases} C_{J_1}^{(m)} & \text{if } m \text{ lies in left subarray} \\ C_{J_2}^{(m-P)} & \text{if } m \text{ lies in middle subarray} \\ C_{J_3}^{(m-Q)} & \text{if } m \text{ lies in right subarray} \end{cases}$$

$$= T_n + \mathbb{1}_{\mathcal{E}_1} \cdot C_{J_1}^{(m)} + \mathbb{1}_{\mathcal{E}_2} \cdot C_{J_2}^{(m-P)} + \mathbb{1}_{\mathcal{E}_3} \cdot C_{J_3}^{(m-Q)}$$

- T_n is the (random) number of comparisons during **partitioning**

Getting Rid of m

- **Complication:** second parameter m in recurrence

$$C_n^{(m)} \stackrel{\mathcal{D}}{=} T_n + \mathbb{1}_{\mathcal{E}_1} \cdot C_{J_1}^{(m)} + \mathbb{1}_{\mathcal{E}_2} \cdot C_{J_2}^{(m-P)} + \mathbb{1}_{\mathcal{E}_3} \cdot C_{J_3}^{(m-Q)}$$

≈ consider simpler quantities

- ① **Random Rank:** $m = M_n \stackrel{\mathcal{D}}{=} \text{Uniform}\{1, \dots, n\}$

← focus in talk

abbreviate $\bar{C}_n := C_n^{(M_n)}$

$$\bar{C}_n \stackrel{\mathcal{D}}{=} T_n + \mathbb{1}_{\mathcal{E}_1} \bar{C}_{J_1} + \mathbb{1}_{\mathcal{E}_2} \bar{C}_{J_2} + \mathbb{1}_{\mathcal{E}_3} \bar{C}_{J_3}$$

- ② **Extreme Rank:** $m = 1$

abbreviate $\hat{C}_n := C_n^{(1)}$

$$\hat{C}_n \stackrel{\mathcal{D}}{=} T_n + \hat{C}_{P-1}$$

- explicit solution for **expectations** possible (generating functions)
- **But:** Requires tedious computations

More elegant shortcut to **asymptotics** of $\mathbb{E}[\bar{C}_n]$ and $\mathbb{E}[\hat{C}_n]$?

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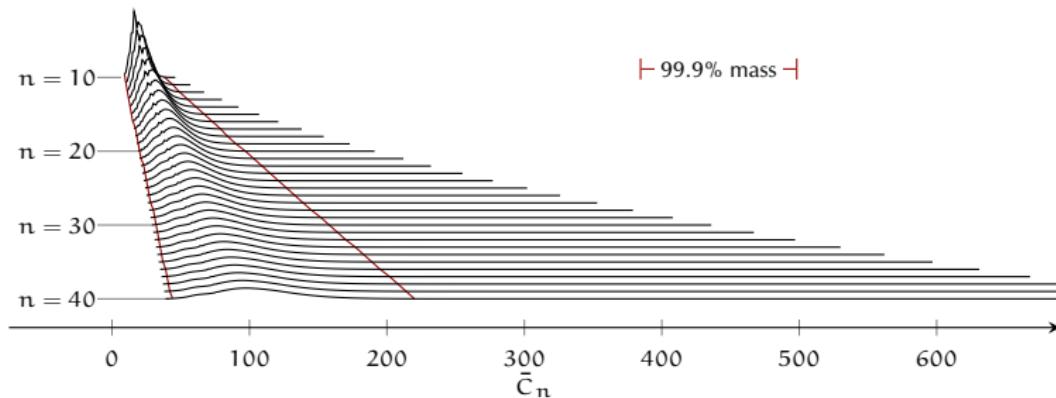
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More elegant shortcut to **asymptotics** of $\mathbb{E}[\bar{C}_n]$ and $\mathbb{E}[\hat{C}_n]$?

Convergence

- **Idea:** Computation easy if we can **drop** index n
i. e. when recurrence “**in equilibrium**”
- For that, we need stochastic **convergence** of \bar{C}_n

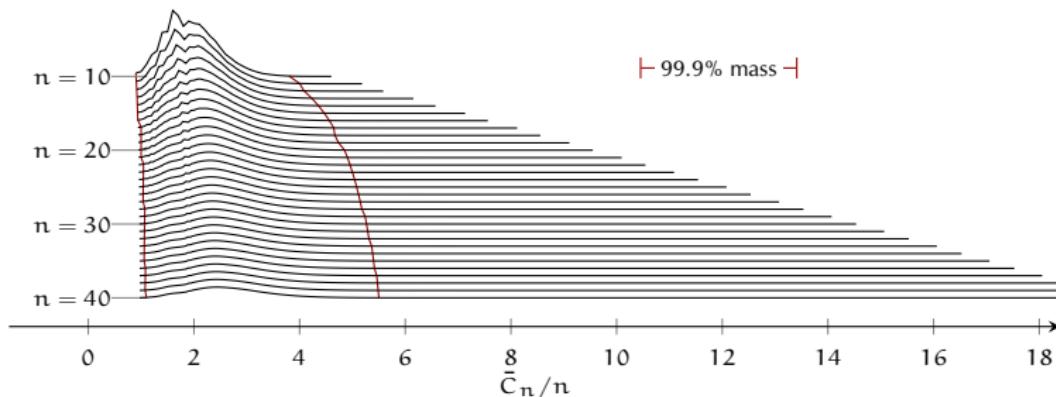


But:

- $\mathbb{E}[\bar{C}_n]$ grows with n
 - high mass region moves with n
- $\left. \begin{array}{l} \text{---} \\ \bar{C}_n \text{ does not converge} \end{array} \right\}$

Convergence

- **Idea:** Computation easy if we can **drop** index n
i. e. when recurrence “**in equilibrium**”
- Try **normalized** variables $\bar{C}_n^* := \frac{\bar{C}_n}{n}$ instead:



- $\mathbb{E}[\bar{C}_n^*]$ seems constant
 - range of high mass looks bounded
 - Works because of property of Quickselect: $\mathbb{E}[\bar{C}_n] = \mathcal{O}\left(\sqrt{\text{Var}(\bar{C}_n)}\right)$
- $\left. \begin{array}{l} \mathbb{E}[\bar{C}_n^*] \text{ seems constant} \\ \text{range of high mass looks bounded} \end{array} \right\} \bar{C}_n^* \text{ might converge}$

The Contraction Method

- Rewrite recurrence: (Write as sum)

$$\bar{C}_n \stackrel{\mathcal{D}}{=} T_n + \mathbb{1}_{\mathcal{E}_1} \bar{C}_{J_1} + \mathbb{1}_{\mathcal{E}_2} \bar{C}_{J_2} + \mathbb{1}_{\mathcal{E}_3} \bar{C}_{J_3}$$

- **Contraction Method:**

*Convergence of coefficients + contraction condition
implies convergence to fixpoint solution.*

~~ have to show: (all convergences in L_1 -norm)



The Contraction Method

- Rewrite recurrence: (Divide by n)

$$\bar{C}_n \stackrel{\mathcal{D}}{=} T_n + \sum_{i=1}^3 \mathbb{1}_{\mathcal{E}_i} \bar{C}_{J_i}$$

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The Contraction Method

- Rewrite recurrence: (Rearrange)

$$\frac{\bar{C}_n}{n} \stackrel{\mathcal{D}}{=} \frac{T_n}{n} + \sum_{i=1}^3 \frac{1_{\mathcal{E}_i} \bar{C}_{J_i}}{n} \cdot \frac{J_i}{J_i}$$

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The Contraction Method

- Rewrite recurrence: (use normalized variables)

$$\frac{\bar{C}_n}{n} \stackrel{\mathcal{D}}{=} \frac{T_n}{n} + \sum_{i=1}^3 \mathbb{1}_{\mathcal{E}_i} \frac{J_i}{n} \cdot \frac{\bar{C}_{J_i}}{J_i}$$

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The Contraction Method

- Recurrence for \bar{C}_n^*

$$\bar{C}_n^* \stackrel{\mathcal{D}}{=} T_n^* + \sum_{i=1}^3 \mathbb{1}_{\mathcal{E}_i} \frac{J_i}{n} \cdot \bar{C}_{J_i}^* \quad \text{with } T_n^* := \frac{T_n}{n}$$

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- ① $T_n^* \rightarrow T^*$
- ② $\mathbb{1}_{\mathcal{E}_i} \frac{J_i}{n} \rightarrow A_i^*$
- ③ $\sum_{i=1}^3 \mathbb{E}[|A_i^*|] < 1$

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The Contraction Method

- “Equilibrium” equation for \bar{C}^*

$$\bar{C}^* \stackrel{\mathcal{D}}{=} T^* + \sum_{i=1}^3 A_i^* \cdot \bar{C}^*$$

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- “Equilibrium” equation for \bar{C}^*

(Take **expectation** on both sides)

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- ② $1_{\mathcal{E}_1} \frac{l_i}{n} \rightarrow A_i^*$
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The Contraction Method

- “Equilibrium” equation for \bar{C}^*

(and **solve** for $\mathbb{E} \bar{C}^*$)

$$\mathbb{E} \bar{C}^* = \mathbb{E} T^* + \sum_{i=1}^3 \mathbb{E} A_i^* \cdot \mathbb{E} \bar{C}^*$$

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... *upcoming*

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Probabilistic Model

Need “convenient” probabilistic model:
same probability space for finite n and limit case

- **Natural model:** input elements U_1, \dots, U_n i.i.d. **Uniform(0, 1)**



first two = pivots values

- Our equivalent model:

- Draw spacings S_1, S_2, S_3 on $[0, 1]$ with $S_i \sim \text{Dirichlet}(1, 1, 1)$
- Draw subarray sizes j_1, j_2, j_3 with $j_i \sim \text{Multinomial}(n - 2, S_1, S_2, S_3)$
- Continue recursively

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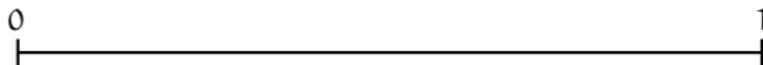
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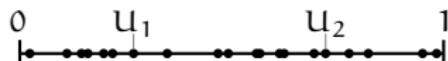
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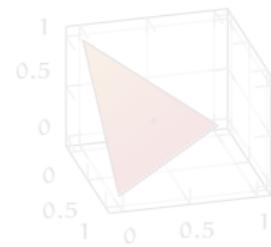
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- induces **pivot values**: $U_1 = S_1, U_2 = S_1 + S_2$



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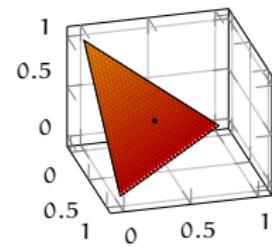


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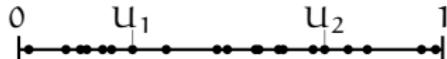
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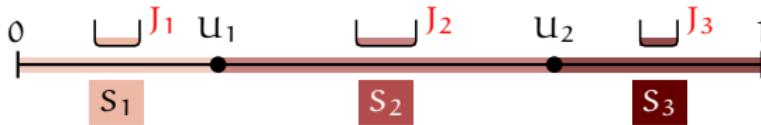
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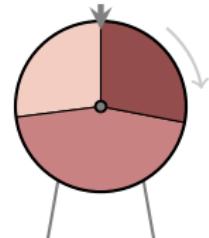
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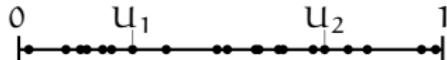
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Probabilistic Model

Need “convenient” probabilistic model:
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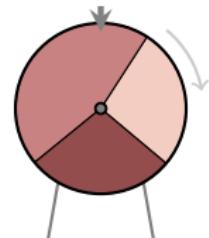
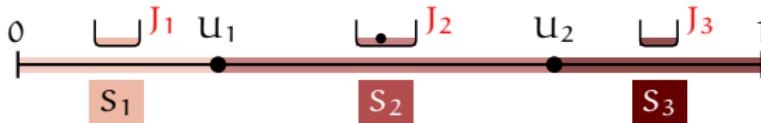
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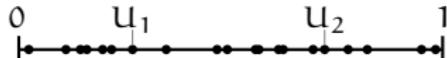


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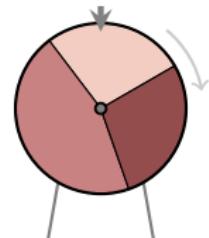
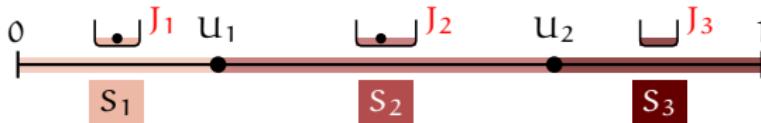
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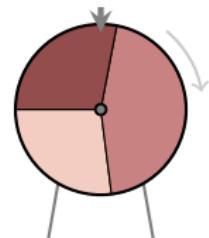
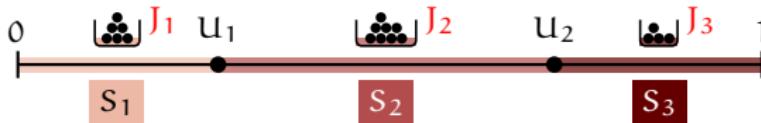
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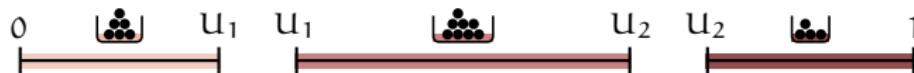
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Distribution of T_n — Repetition

① $T_n^* \rightarrow T^*$

Invariant:



$T_n = \text{number of comparisons in first partitioning step}$

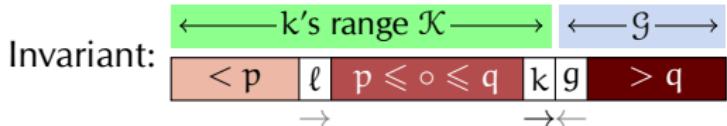
$\sim n$	one for every element
$+ J_2$	second for all medium elements
$+ l @ \mathcal{K}$	second for large elements at C'_k
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$$\left. \begin{aligned} l @ \mathcal{K} &\stackrel{\mathcal{D}}{=} \text{Hypergeometric}(n - 2; J_3, J_1 + J_2) \\ s @ G &\stackrel{\mathcal{D}}{=} \text{Hypergeometric}(n - 2; J_1, J_3) \end{aligned} \right\} \text{conditional on } J$$

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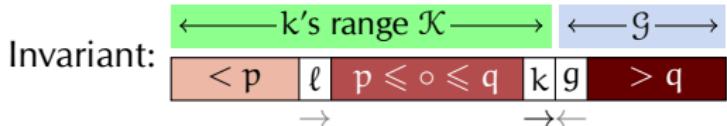
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$$T_n^* = \frac{T_n}{n} = 1 + \frac{J_2}{n} + \frac{l@K}{n} + \frac{s@G}{n}$$

- $\frac{J_2}{n} \rightarrow S_2$ by **law of large numbers**, since $\mathbb{E}[J_i | S] = n \cdot S_i$

- Multinomial and Hypergeometric **concentrated** around mean

$$\rightsquigarrow \frac{l@K}{n} \rightarrow \mathbb{E}\left[\frac{l@K}{n} \mid S\right] \text{ by Chernoff bound arguments}$$

$$= \mathbb{E}\left[\frac{\mathbb{E}[l@K | J]}{n} \mid S\right] = \mathbb{E}\left[\frac{J_3(J_1 + J_2)}{n(n-2)} \mid S\right]$$

$$\sim S_3 \cdot (S_1 + S_2)$$

- $\frac{s@G}{n} \rightarrow S_1 \cdot S_3$ similar

$$\rightsquigarrow T_n^* \rightarrow T^* = 1 + S_2 + S_3(2S_1 + S_2)$$

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$$② \mathbb{1}_{\mathcal{E}_i} \frac{J_i}{n} \rightarrow A_i^*$$

- standard computation:

$$\mathbb{1}_{\mathcal{E}_1} \frac{J_1}{n} \rightarrow \mathbb{1}_{\mathcal{F}_1} \cdot S_1 \quad \text{with } \mathcal{F}_1 = \{V < S_1\}$$

- $i = 2, 3$ similar

$$③ \sum_{i=1}^3 \mathbb{E}[|A_i^*|] < 1$$

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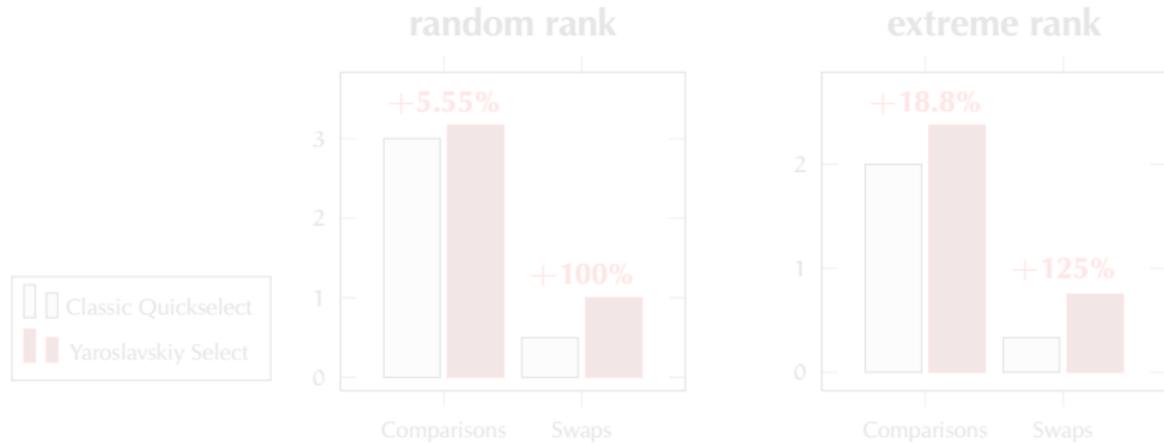
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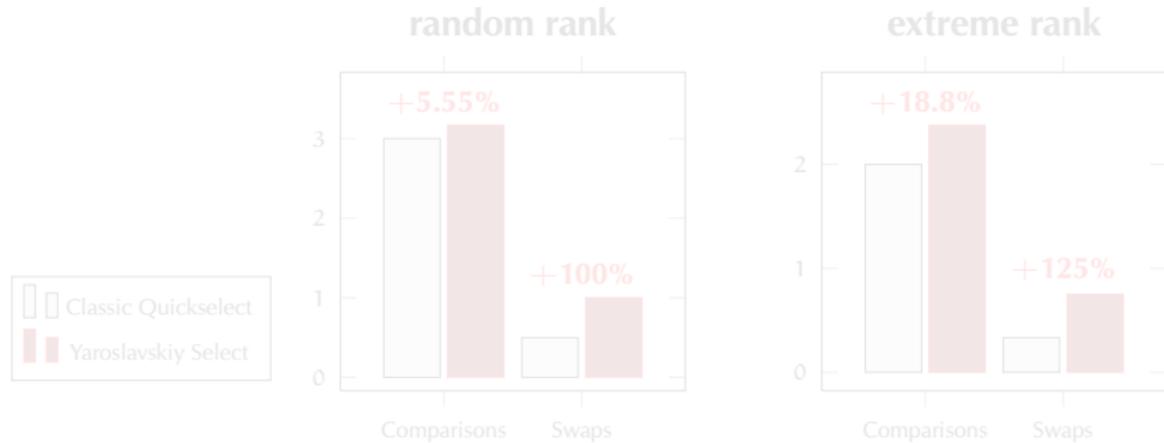
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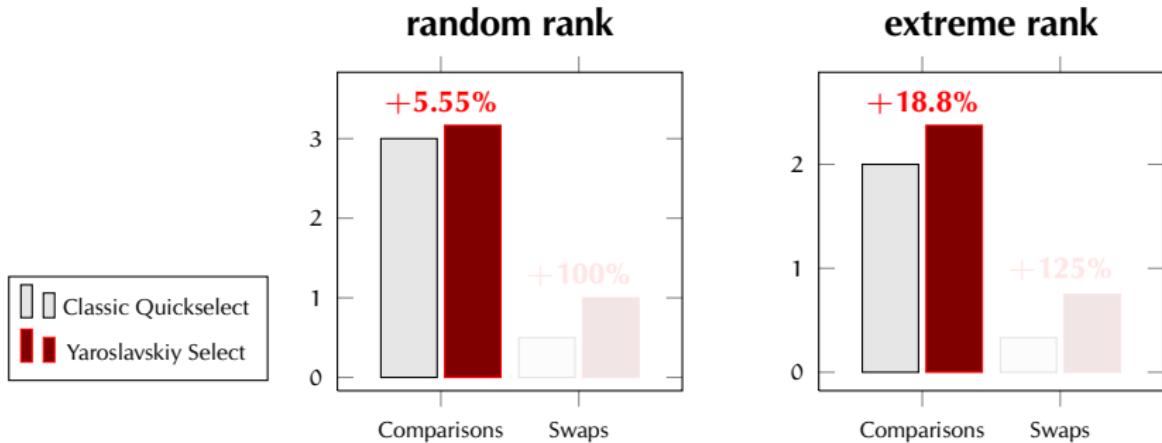
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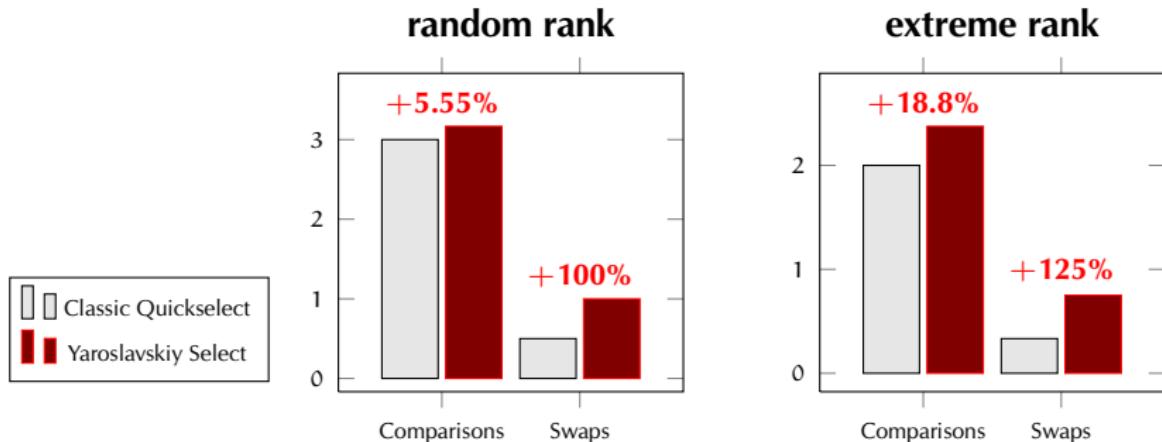
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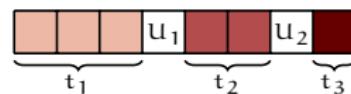


Pivot Sampling

- successful optimization of Quicksort/-select: **median of three**
- **Here:** generalized pivot selection scheme
 - ① Choose random sample of **k** elements
 - ② **Sort** the sample
 - ③ Select pivots s. t. in sorted sample

t₁ smaller ,
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Example with
 $k = 8$ and $\mathbf{t} = (3, 2, 1)$:



Our stochastic model nicely **generalizes** to pivot sampling:

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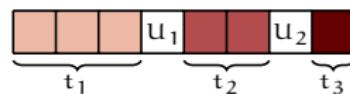
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inconvenient for interpretation ...

- Limiting case for large sample:

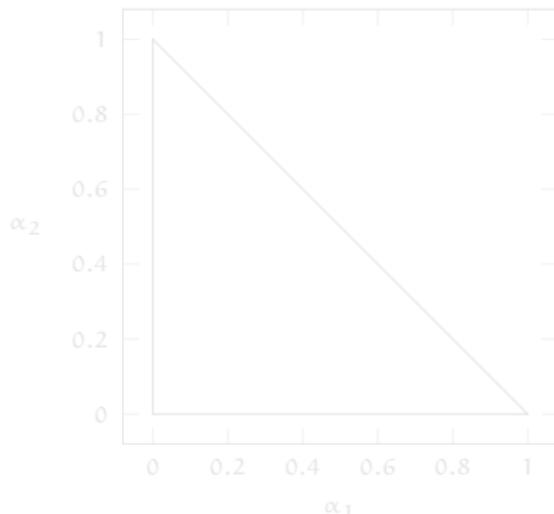
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\triangleq take exact quantiles as pivots

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→ optimal choice is not symmetric

→ choose $\alpha_1, \alpha_2, \alpha_3$ with $\alpha_1 < \alpha_2 < \alpha_3$
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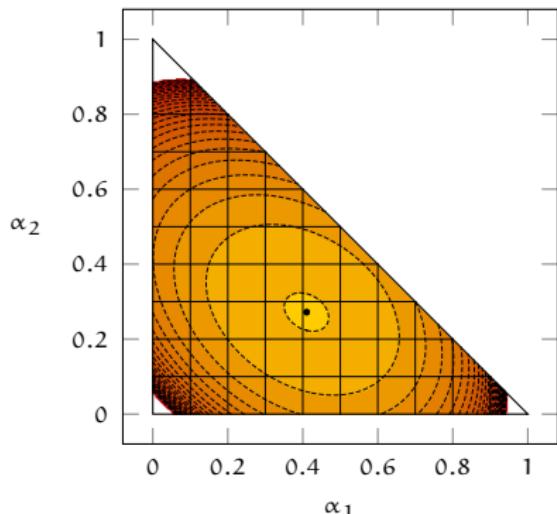
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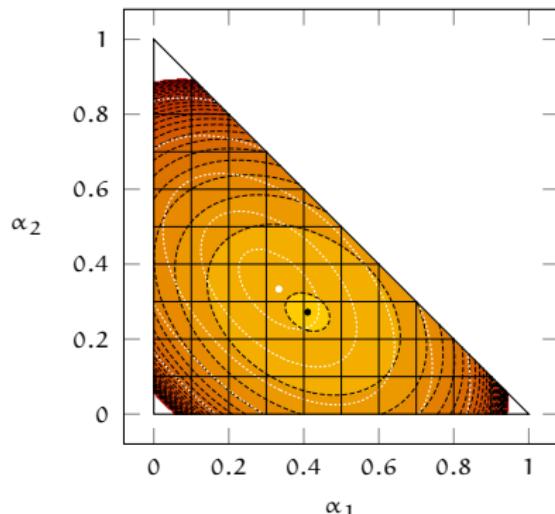
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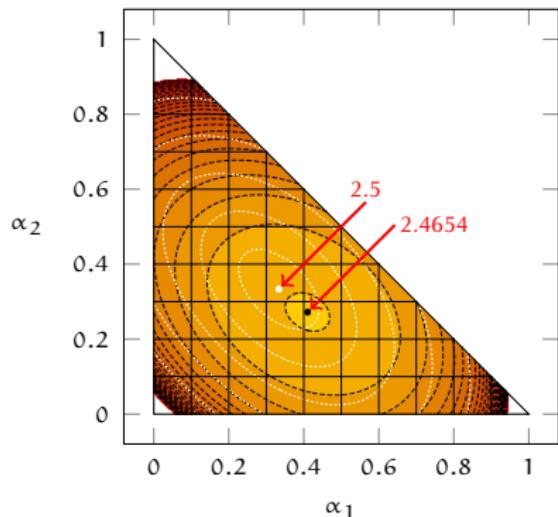
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Conclusion

Practitioners' Lesson:

- Yaroslavskiy's dual-pivoting **not** helpful for selection

Analyzers' Lesson:

- **expected** costs of Quickselect derivable by **contraction method**
- pivot sampling included naturally

References & Further Reading



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Results — Variances

- more diligence in analysis: convergences hold in L_2
- $\rightsquigarrow \text{Var}(\bar{C}_n^*) \rightarrow \text{Var}(\bar{C}^*)$ and $\text{Var}(\bar{C}_n) \sim \text{Var}(\bar{C}^*)n^2$

	random rank	extreme rank	
		min	max
classic Quickselect	1	0.5	
Yaroslavskiy Select	0.694	0.263	0.358

- variances **lower** than for classic Quickselect
- asymmetry** for extreme ranks:
 - T^* **not** symmetric in S
 - \rightsquigarrow Cost of selecting minimum and maximum have **different distribution** (but same mean)

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